Python with Robots Mission 3 Lab Data Sheet – OBJ 7			Name:	
Obj 7 Get Moving: How far does the CodeBot move if both wheels have the same power, with a given delay?				
Wheel power setting		Sleep delay		Distance traveled
Obj 8 Rotation Time: What angle does the CodeBot turn with a given wheel power and delay?				
Left Wheel power	Right Wheel power		Sleep delay	Angle and rotation (which way)
Planning Guide: Turn this paper over. Plan your navigation square by using a flowchart of pseudocode.				